

图神经网络七日打卡营

小斯妹 百度PGL团队成员



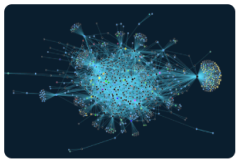
2020.11.26



昨天的一些问题

飞桨 PaddlePaddle

Message Passing 相关函数的参数解释：



图神经网络7日打卡营

飞桨深度学习学院

2020/11/04 - 2021/02/12

分享

课节 共4课节

课节1: 预习 >

课节2: 图学习初印象 >

课节3: 图游走类模型 >

课节4: 图神经网络算法（一） v

已学习 [项目]PGL图学习公开课Lesson3-Message Passi... 继续学习 重新学习

未学习 [视频]3-1 课前答疑与引入 开始学习

未学习 [视频]3-2 GCN 开始学习

已学习 [视频]3-3 GAT与Message Pass 继续学习

```
def gcn_layer(gw, feature, hidden_size, activation, name, norm=None): 度
    # send函数
    def send_func(src_feat, dst_feat, edge_feat):
        ...
```

PGL源码： <https://github.com/PaddlePaddle/PGL/blob/main/examples/gcn/train.py#L38>

```
# normalize
```

```
indegree = dataset.graph.indegree()
```

```
norm = np.zeros_like(indegree, dtype="float32")
```

```
norm[indegree > 0] = np.power(indegree[indegree > 0], -0.5)
```

```
dataset.graph.node_feat["norm"] = np.expand_dims(norm, -1)
```

$D^{-\frac{1}{2}}$, 压缩为一维向量
(num_nodes, 1)

PGL 源码：

<https://github.com/PaddlePaddle/PGL/blob/main/pgl/layers/conv.py#L27>

```
1  
2     if norm is not None:  
3         feature = feature * norm  
4     }  
5  
6     msg = gw.send(send_src_copy, nfeat_list=[("h", feature)])  
7  
8  
9     if size > hidden_size:  
10        output = gw.recv(msg, "sum")  
11    }  
12    else:  
13        output = gw.recv(msg, "sum")  
14        output = L.fc(output,  
15                       size=hidden_size,  
16                       bias_attr=False,  
17                       param_attr=fluid.ParamAttr(name=name))  
18  
19  
20    if norm is not None:  
21        output = output * norm  
22    }
```

$$H^{(l+1)} = \sigma \left(\tilde{D}^{-\frac{1}{2}} \tilde{A} \tilde{D}^{-\frac{1}{2}} H^{(l)} W^{(l)} \right)$$

课程大纲

飞桨 PaddlePaddle



第一课：图学习初印象

- 图学习概述、入门路线
- 实践：环境搭建

第二课：图游走类算法

- DeepWalk, node2vec, metapath2vec
- 实践：DeepWalk

第三课：图神经网络算法(一)

- GCN, GAT
- 实践：GCN, GAT

第四课：图神经网络算法(二)

- 图采样、邻居聚合
- 实践：GraphSage

第五课：GNN 进阶

- ERNIESage, UniMP
- 实践：ERNIESage 代码讲解

后续：新冠项目实战，带你助力疫情防控

参考材料：

- 斯坦福CS224W课程：<http://cs224w.stanford.edu>
- 图学习库 PGL：<https://github.com/PaddlePaddle/PGL>

第四课 图神经网络算法(二)

小斯妹 百度PGL团队成员

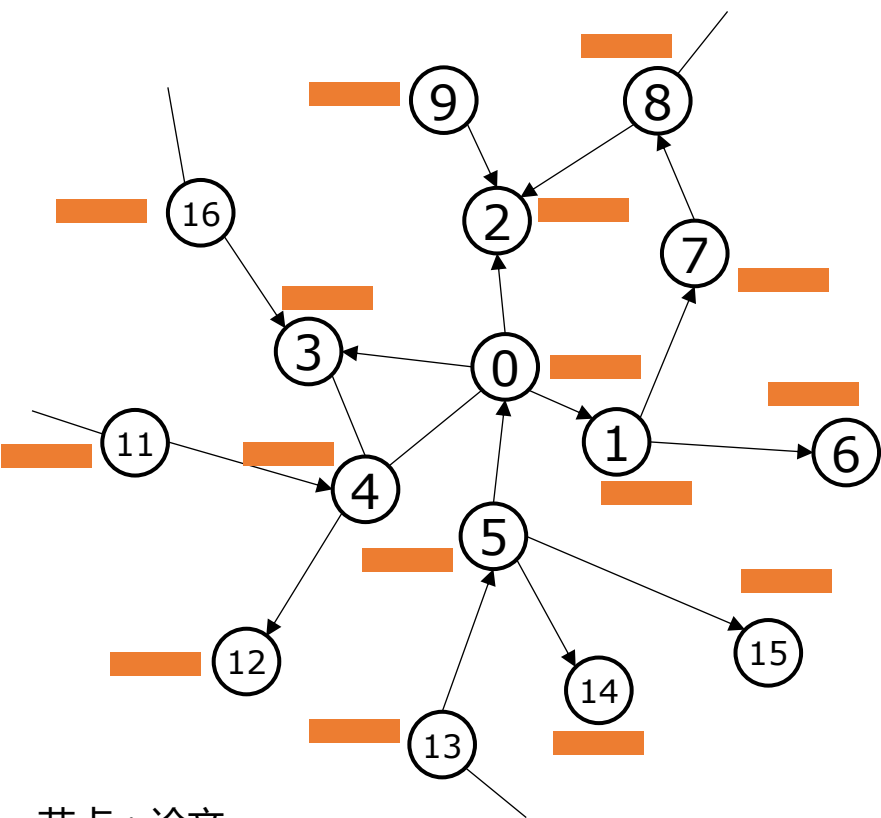


2020.11.26



回顾上节课任务

Cora: 引用论文节点分类数据集(7个分类类别)

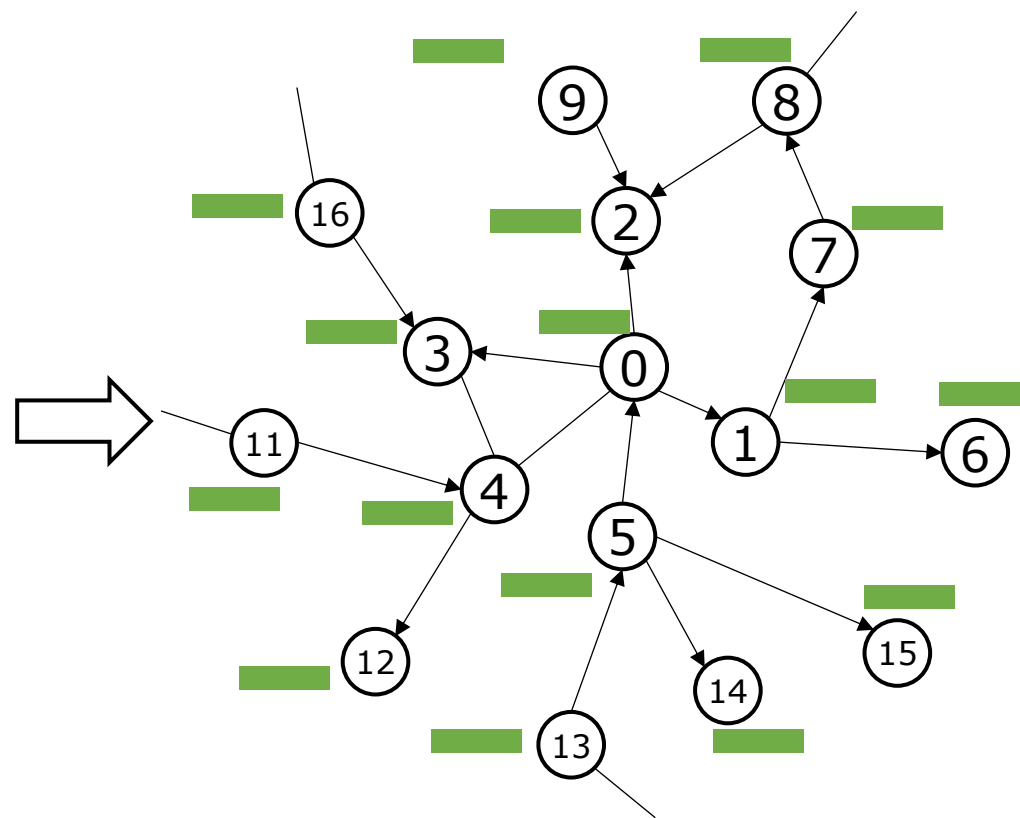


节点：论文
边：论文引用关系
节点特征：**1433维**one-hot 词向量表示

作业部分

GCN layer
GAT layer

hidden_size=64

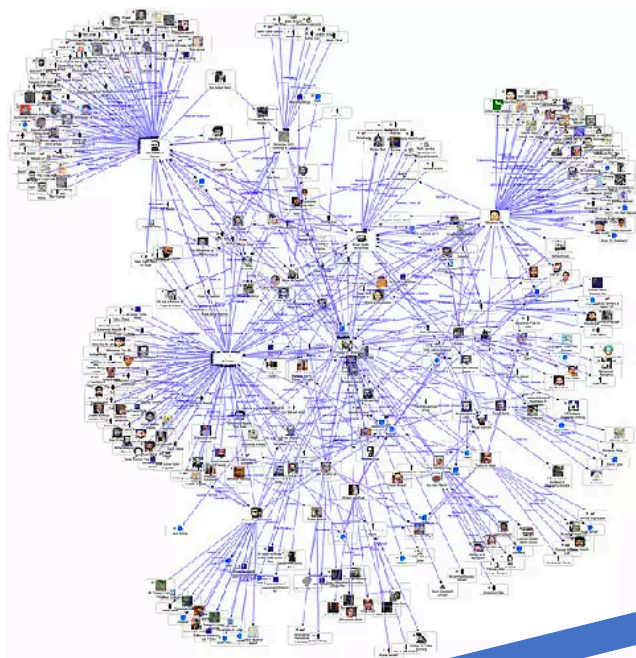


Cora: 2708个节点, 5429条边



为什么要图采样

互联网中动辄**亿量级**的图数据



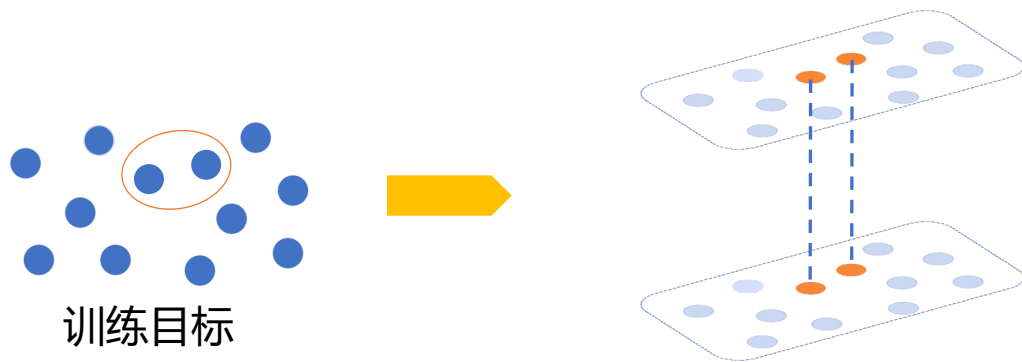
当代的GPU/CPU资源受限



无法一次性全图送入计算资源，需要借鉴深度学习中的MiniBatch

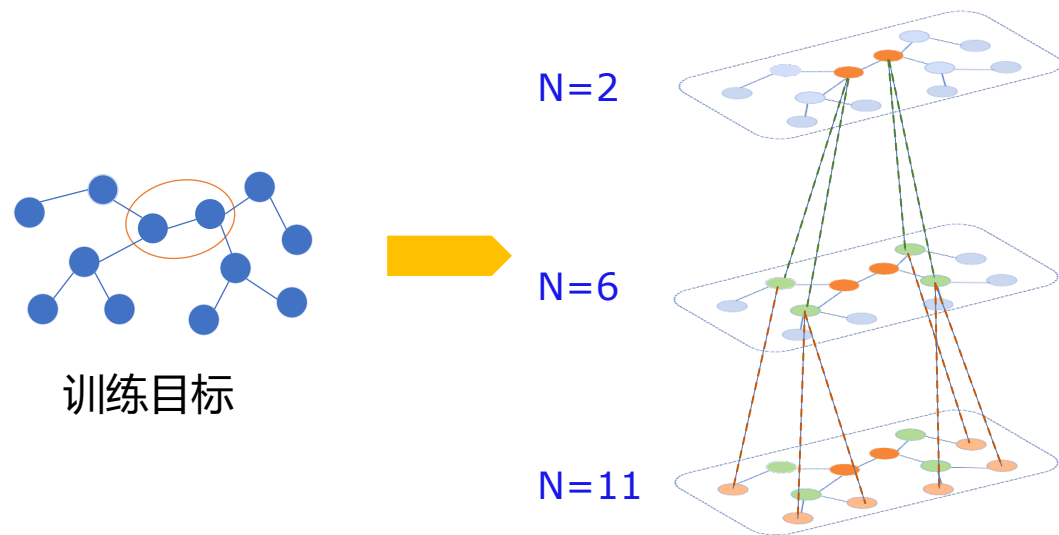
为什么要图采样

MiniBatch训练



传统深度学习

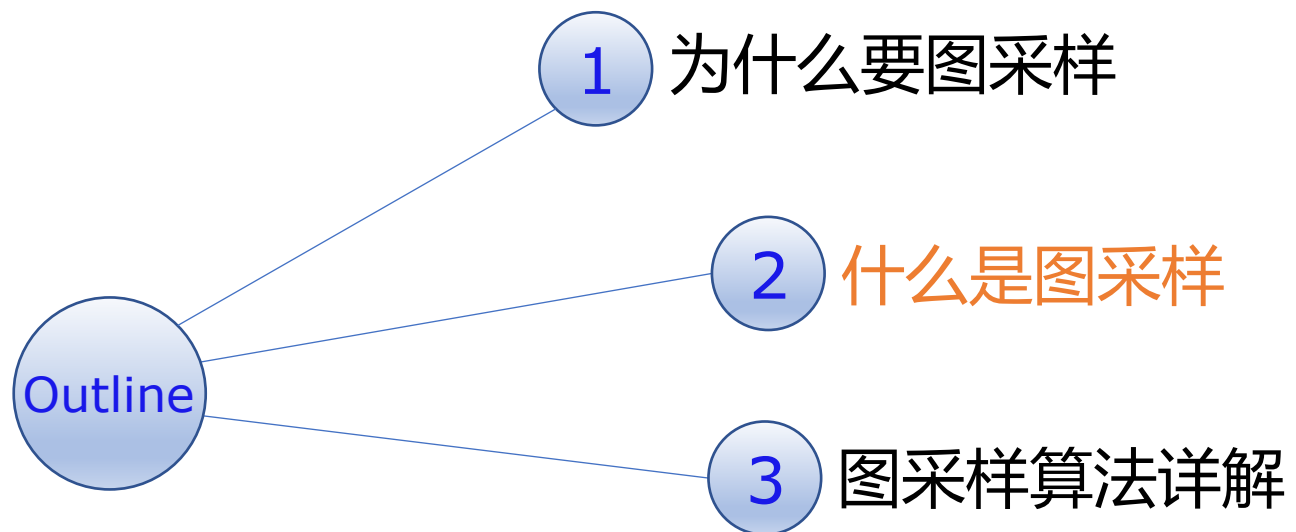
- 单batch为若干个**样本**
- 样本之间**无**依赖，多层样本计算量**固定**



图神经网络

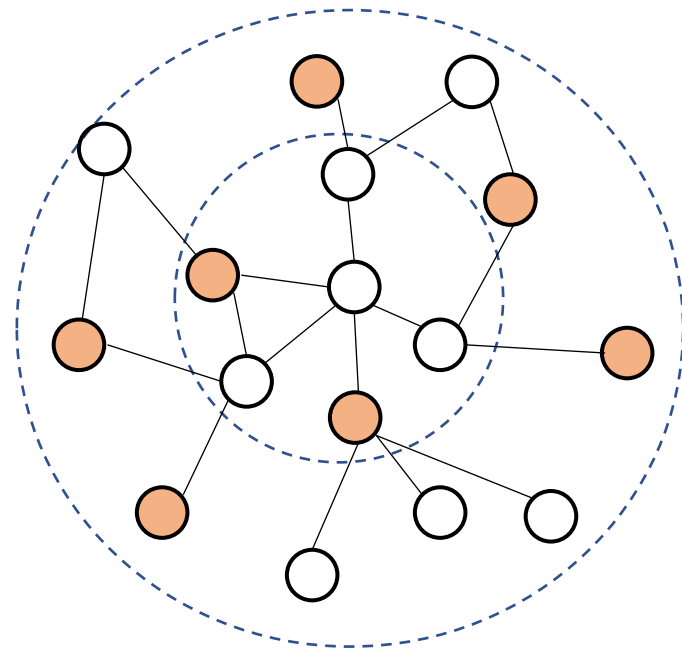
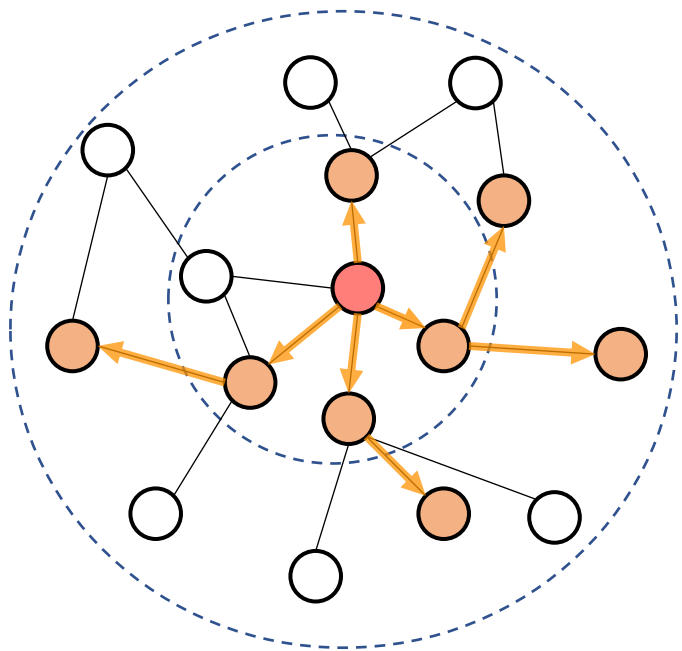
- 单batch为若干个**节点**
- 节点之间**相互**依赖，多层节点计算量**爆炸**

涉及计算的节点随层数增加呈指数增长



什么是图采样

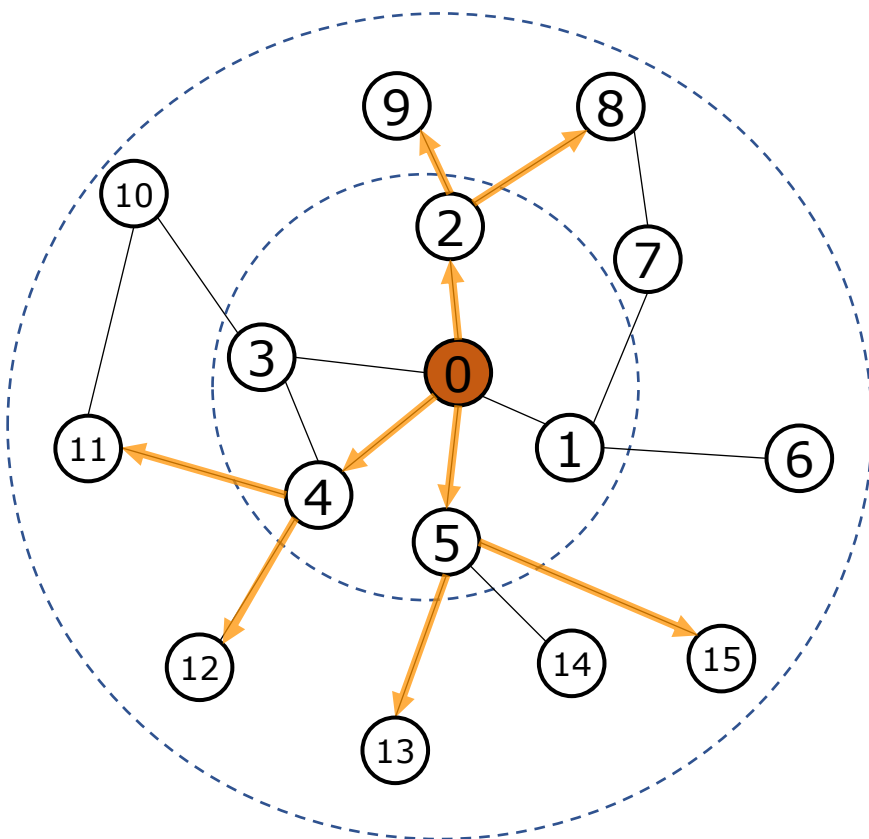
子图采样而不是随机采样



一个节点表示由它的邻居决定



1, 邻居采样



```
graph = build_graph()
start_nodes = [0]

layer1_nodes = graph.sample_predecessor(start_nodes, 3)

layer1_edges = []
for dst_node, src_nodes in zip(start_nodes, layer1_nodes):
    for node in src_nodes:
        layer1_edges.append((node, dst_node))

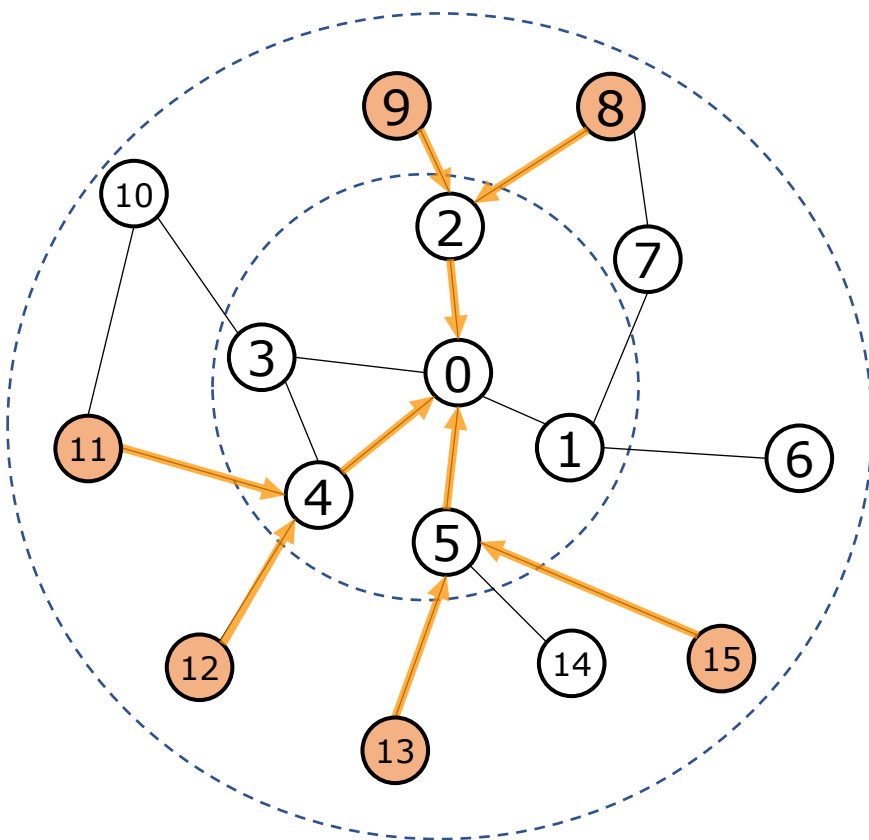
print("layer1_nodes: ", layer1_nodes)
print("layer1_edges: ", layer1_edges)
# layer1_nodes: [array(2, 4, 5)]
# layer1_edges: [(2, 0), (4, 0), (5, 0)]
```

```
start_nodes = layer1_nodes[0].tolist()
layer2_nodes = graph.sample_predecessor(start_nodes, 2)

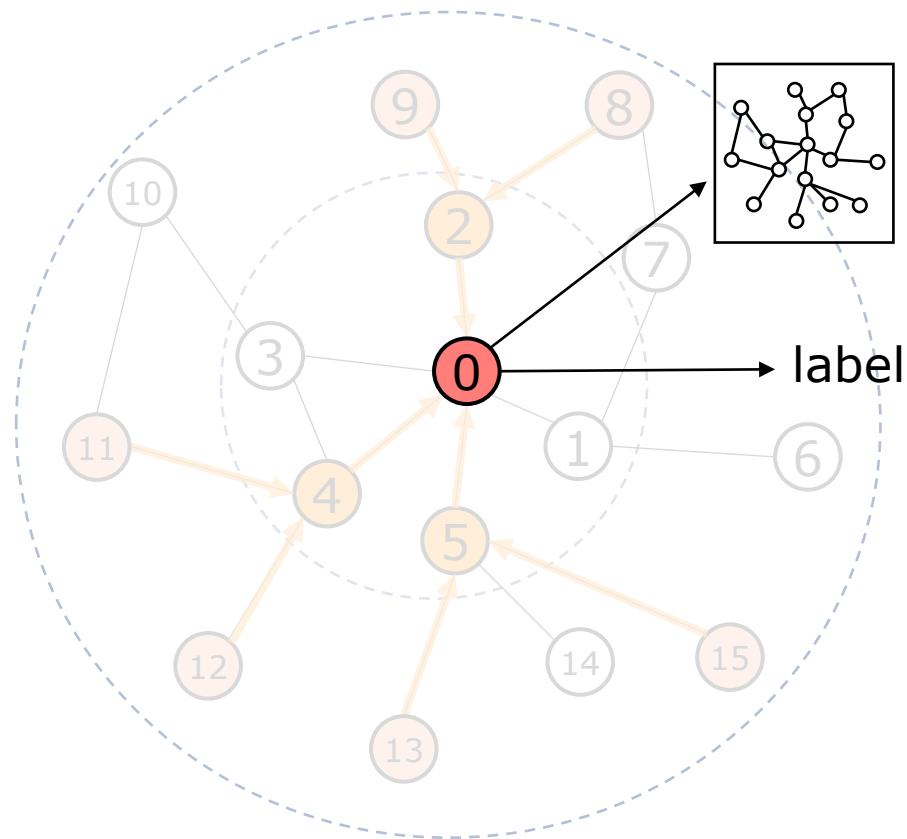
layer2_edges = []
for dst_node, src_nodes in zip(start_nodes, layer2_nodes):
    for node in src_nodes:
        layer2_edges.append((node, dst_node))

print("layer2_nodes: ", layer2_nodes)
print("layer2_edges: ", layer2_edges)
# layer2_nodes: [array([8, 9]), array([11, 12]), array([13, 15])]
# layer1_edges: [(8, 2), (9, 2), (11, 4), (12, 4), (13, 5), (15, 5)]
```

2, 邻居聚合

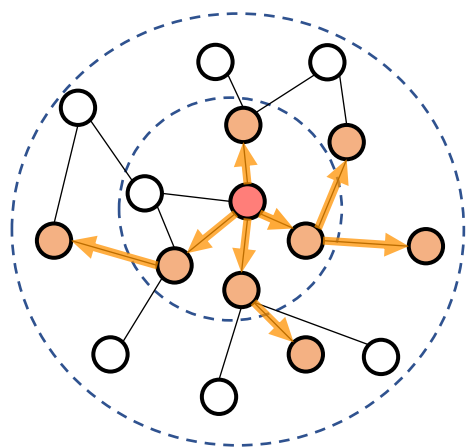


3, 节点预测



邻居采样的优点

1、极大减少训练计算量

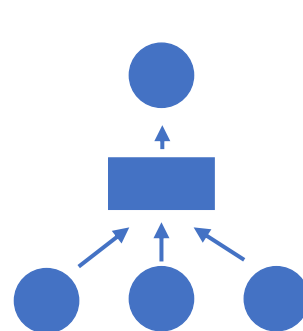


$$N^K \rightarrow M^K$$

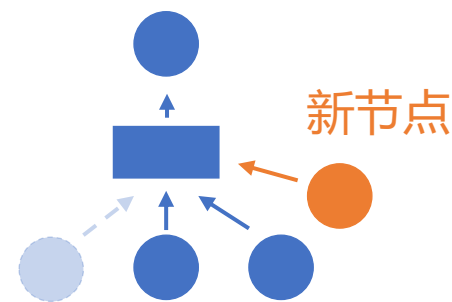
$(N^K \gg M^K)$

N : 平均邻居数
M : 采样数
K : 训练层数

2、允许泛化到新连接关系



Train阶段



Infer阶段

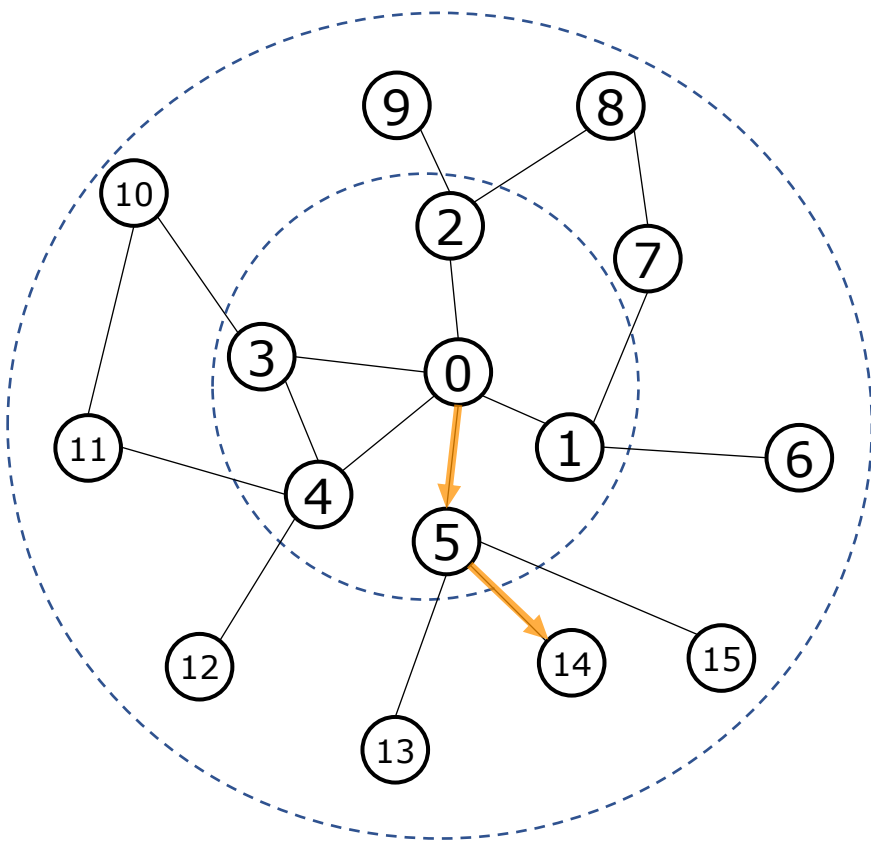
采样时只能选取真实的邻居节点吗？

采样时只能选取真实的邻居节点吗？

PinSAGE：通过多次随机游走，按游走经过的**频率**选取邻居

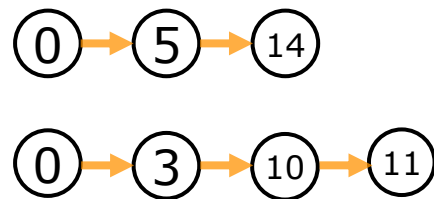
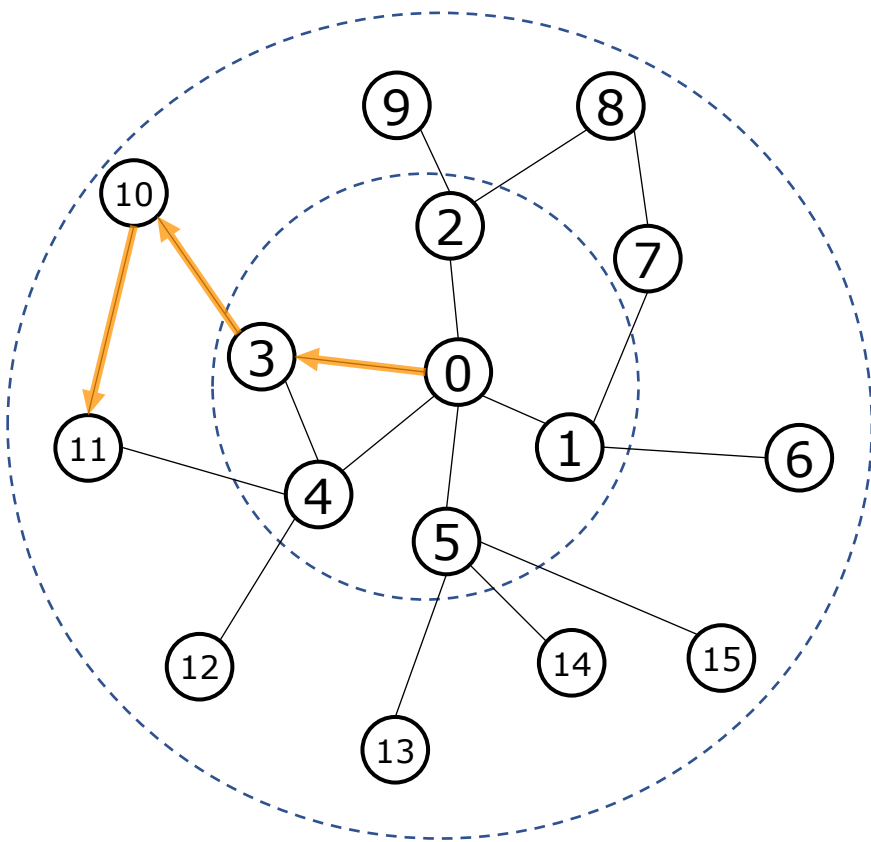
采样时只能选取真实的邻居节点吗？

PinSAGE：通过多次随机游走，按游走经过的**频率**选取邻居



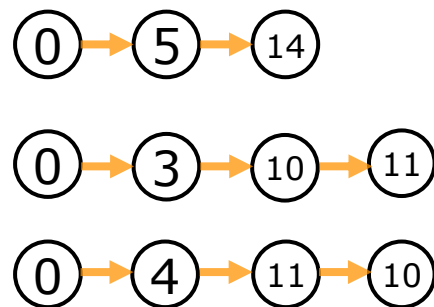
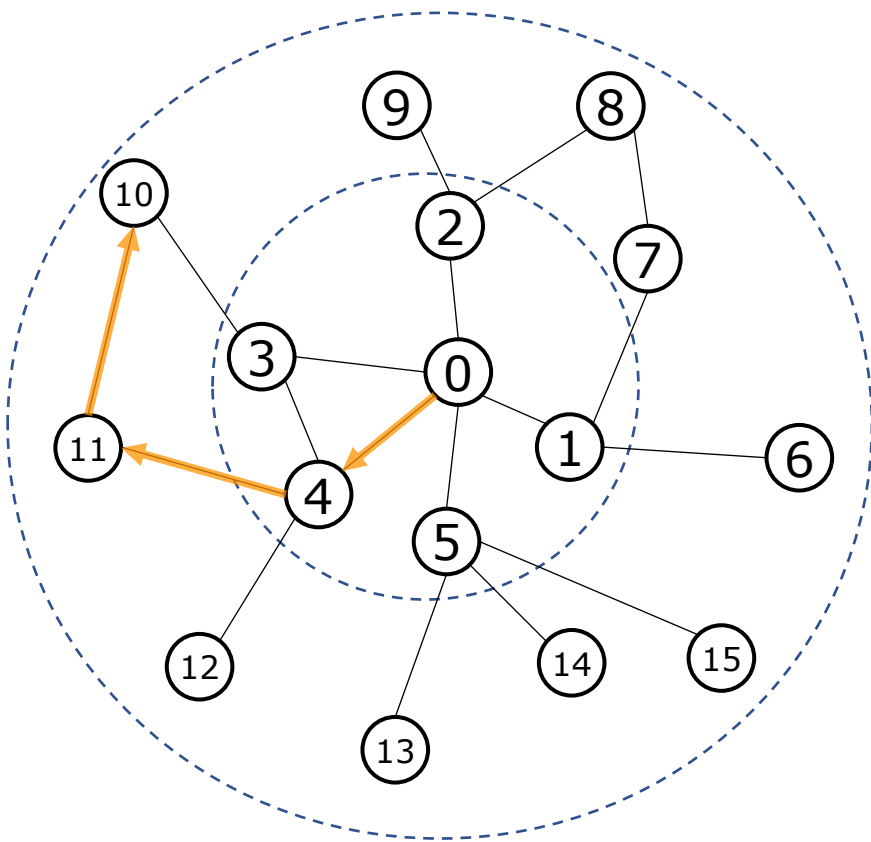
采样时只能选取真实的邻居节点吗？

PinSAGE：通过多次随机游走，按游走经过的**频率**选取邻居



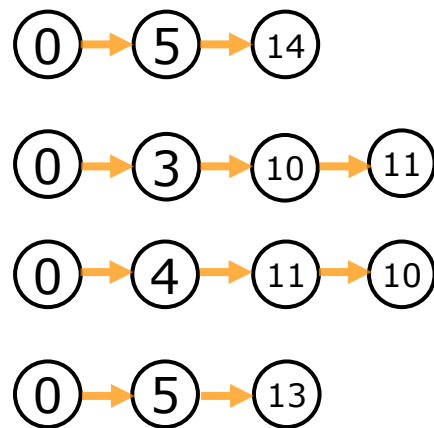
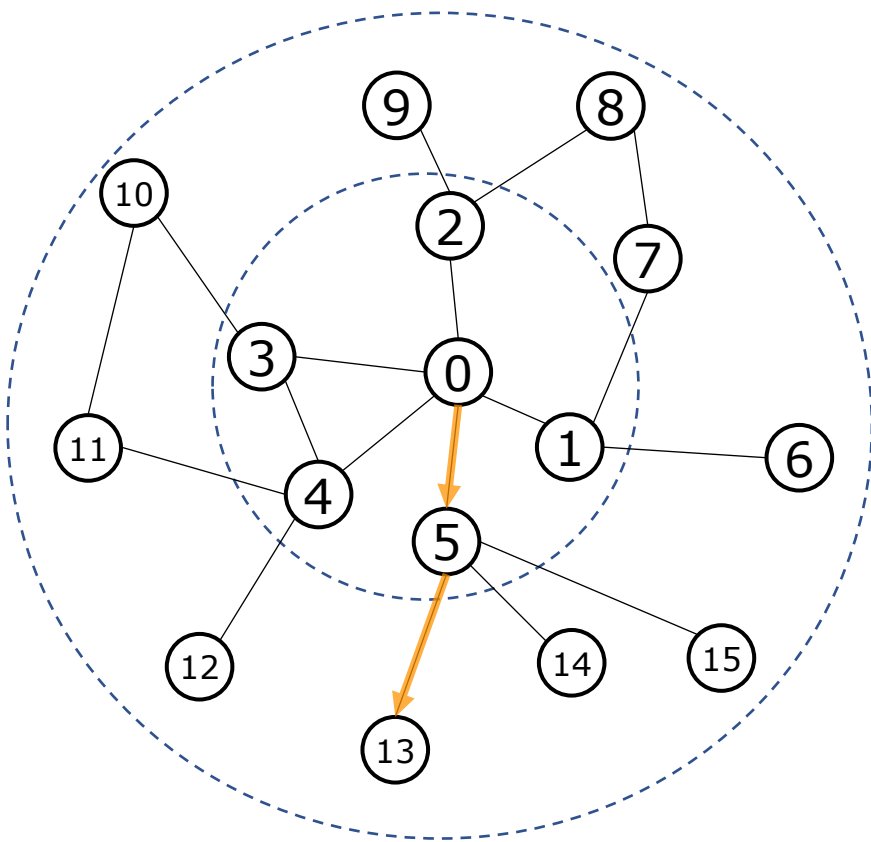
采样时只能选取真实的邻居节点吗？

PinSAGE：通过多次随机游走，按游走经过的**频率**选取邻居



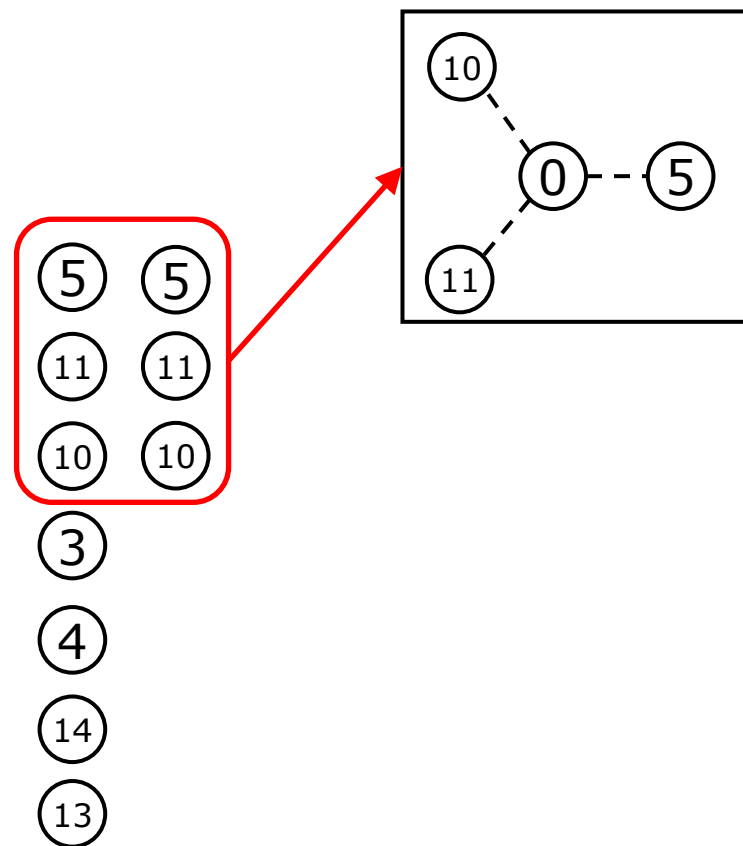
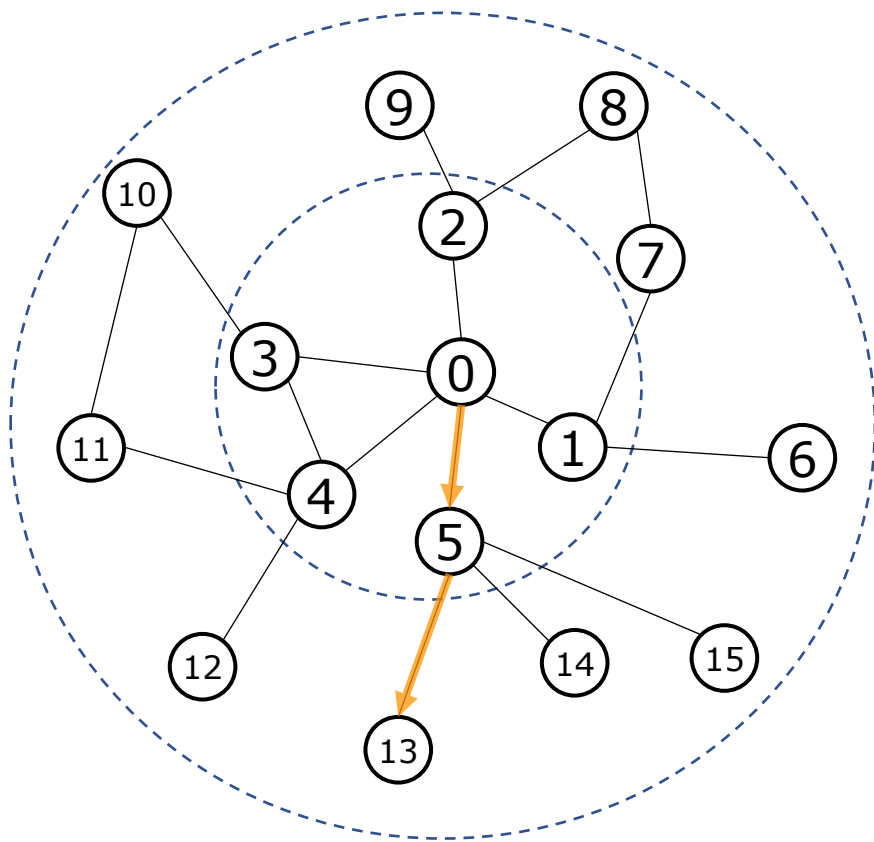
采样时只能选取真实的邻居节点吗？

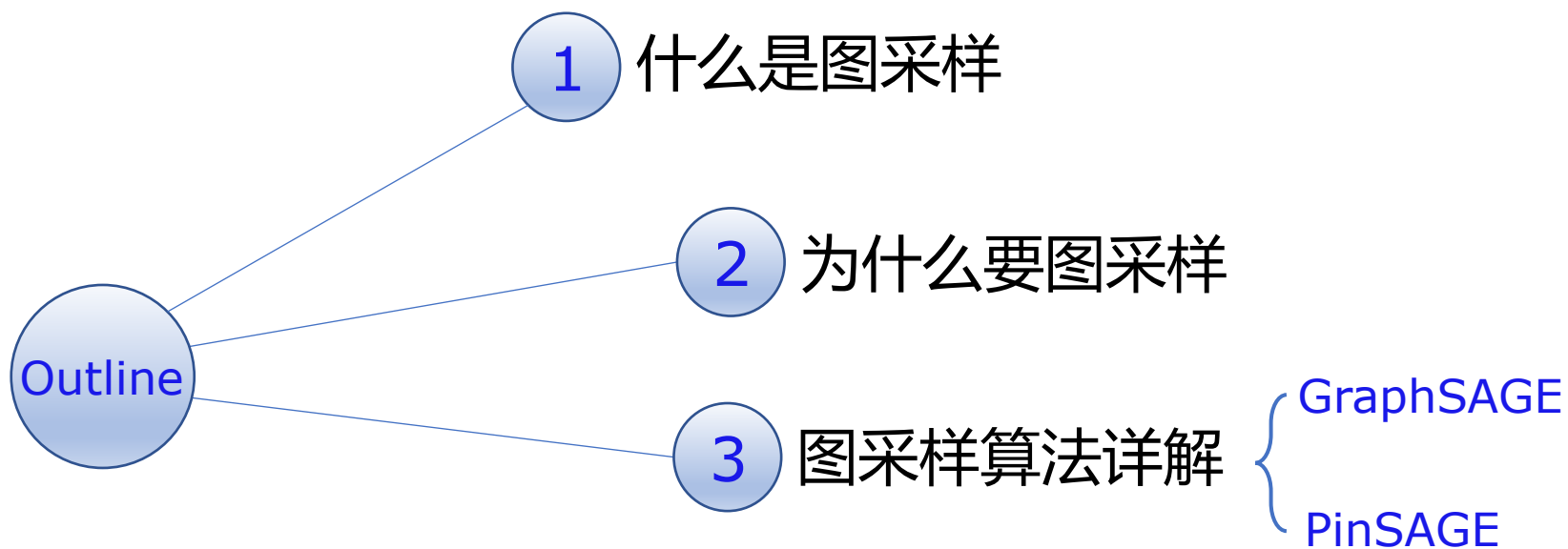
PinSAGE：通过随机游走，按游走经过的**频率**选取邻居



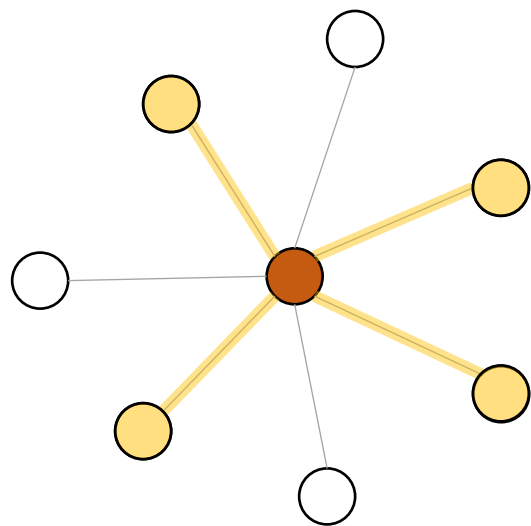
采样时只能选取真实的邻居节点吗？

PinSAGE：通过随机游走，按游走经过的**频率**选取邻居

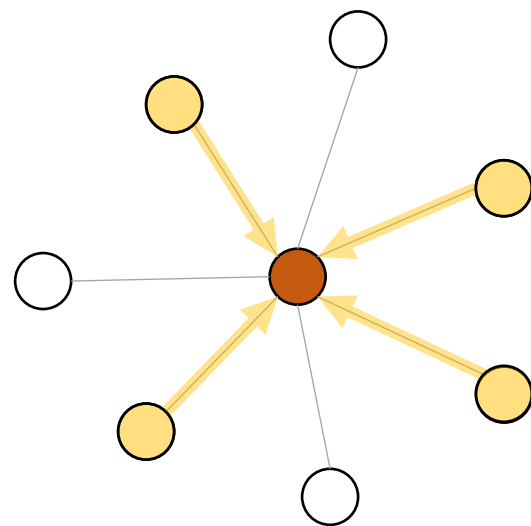




图采样之后——邻居聚合

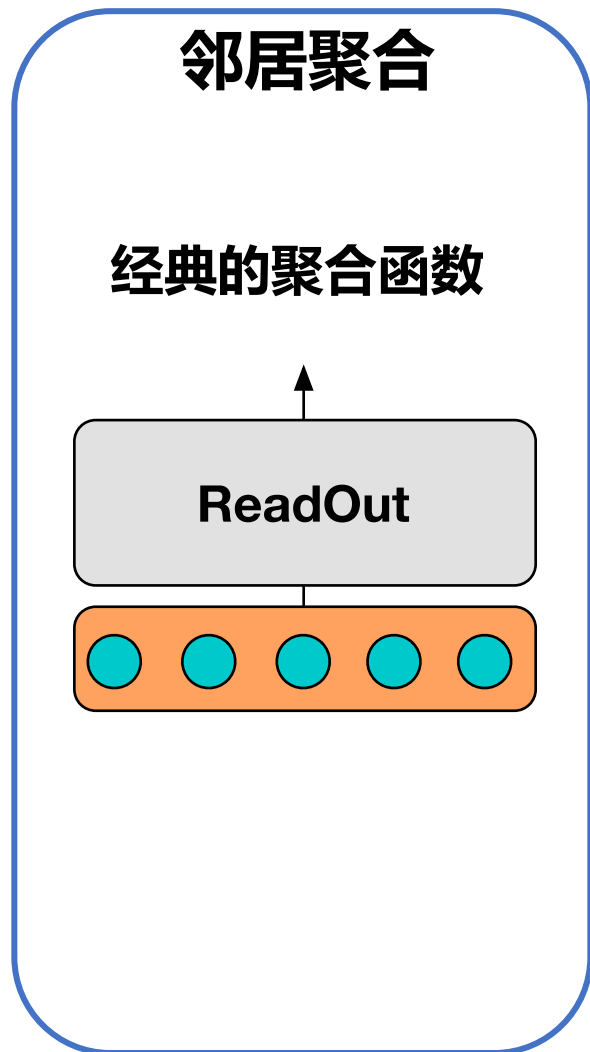


图采样



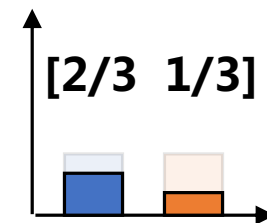
邻居聚合

邻居聚合



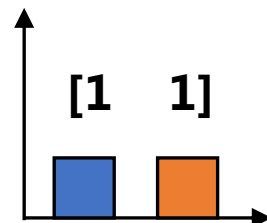
$$\text{Mean} \left(\begin{matrix} [1\ 0] & [1\ 0] \\ [0\ 1] & [0\ 1] \\ [1\ 0] & [1\ 0] \end{matrix} \right)$$

=



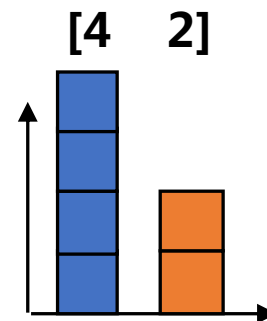
$$\text{Max} \left(\begin{matrix} [1\ 0] & [1\ 0] \\ [0\ 1] & [0\ 1] \\ [1\ 0] & [1\ 0] \end{matrix} \right)$$

=



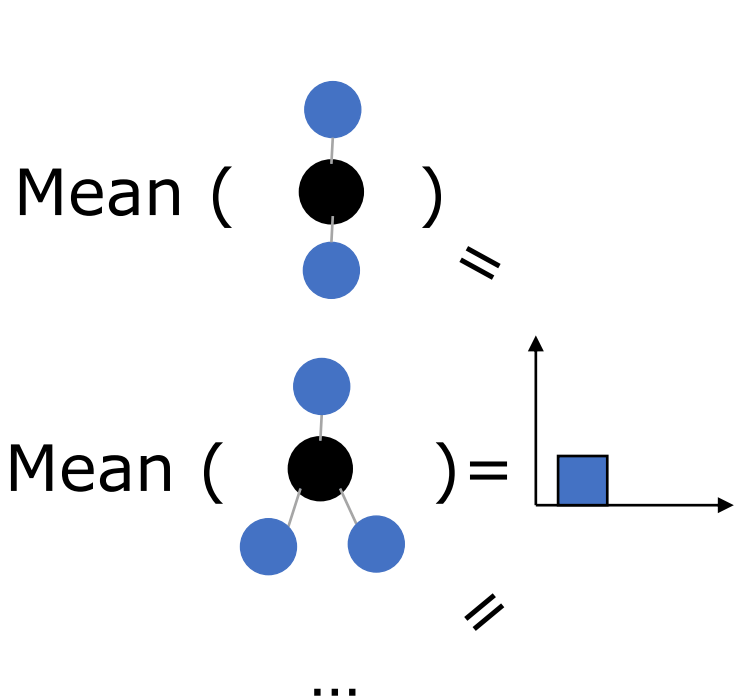
$$\text{Sum} \left(\begin{matrix} [1\ 0] & [1\ 0] \\ [0\ 1] & [0\ 1] \\ [1\ 0] & [1\ 0] \end{matrix} \right)$$

=



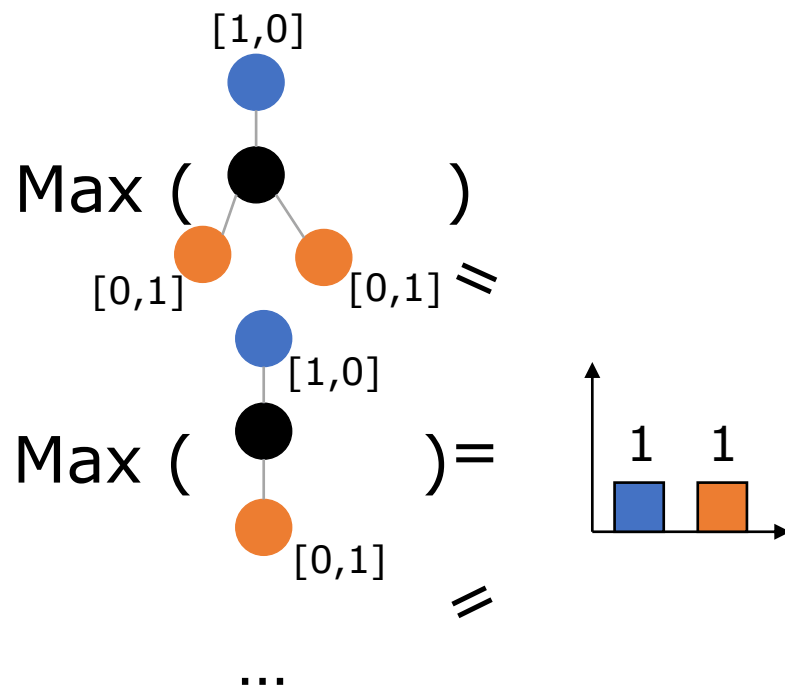
邻居聚合

评估聚合表达能力的指标**单射** (一对一映射)



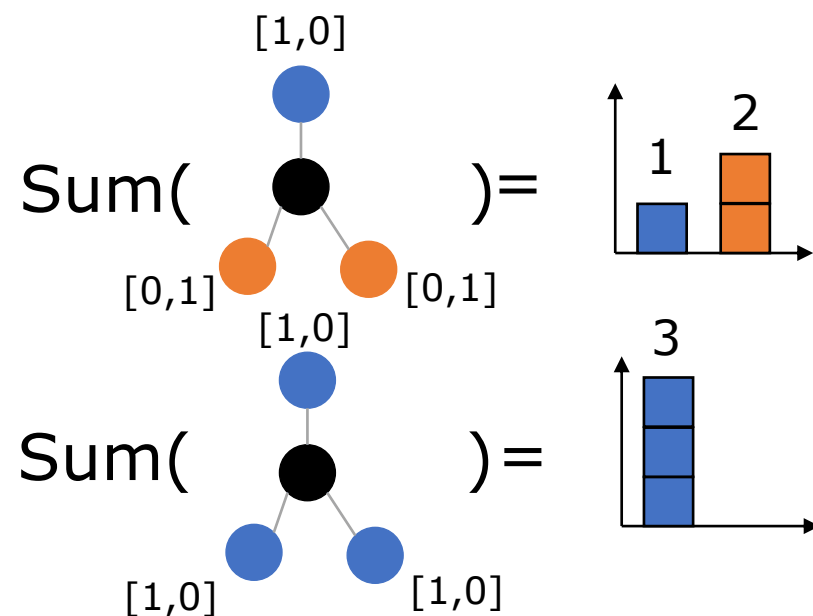
非单射 

Mean倾向学分布



非单射 

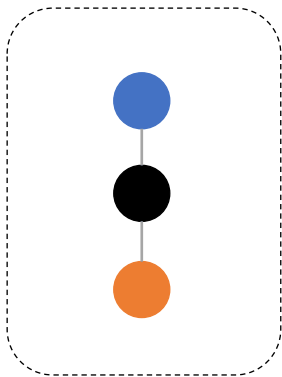
Max倾向忽略重复值



单射 

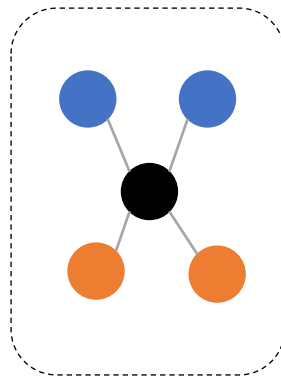
Sum保留完整信息

单射可以保证对聚合后的结果可区分



子图1

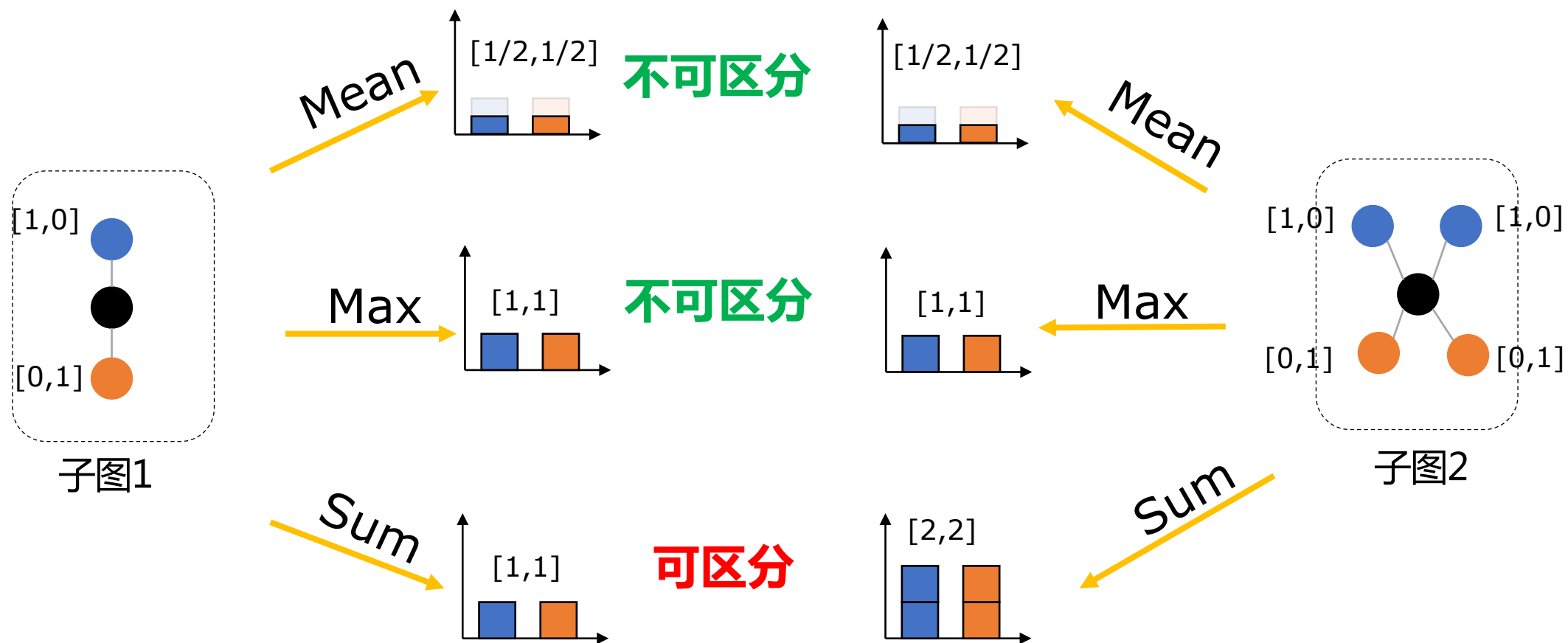
VS



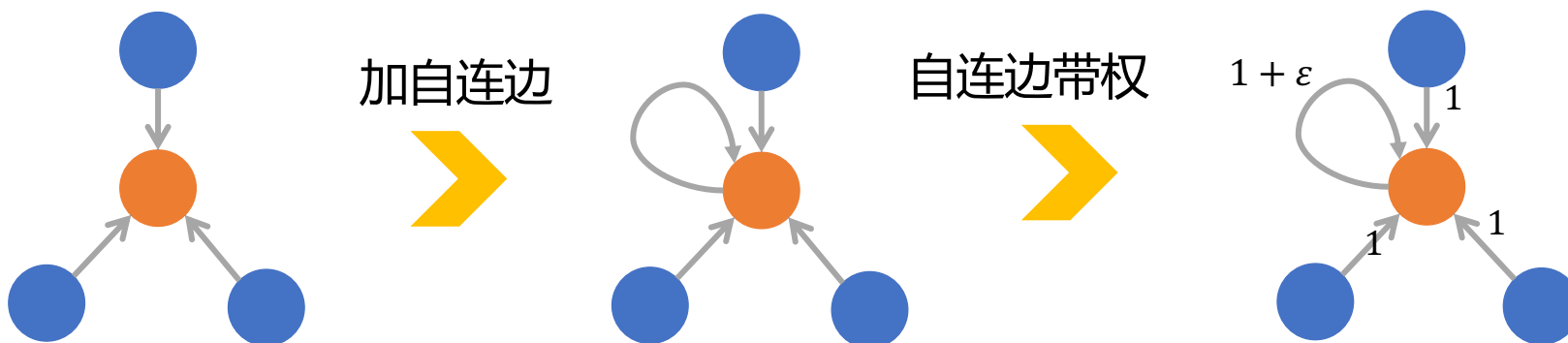
子图2

邻居聚合

单射可以保证对聚合后的结果可区分



基于单射的Graph Isomorphism Net (GIN)模型

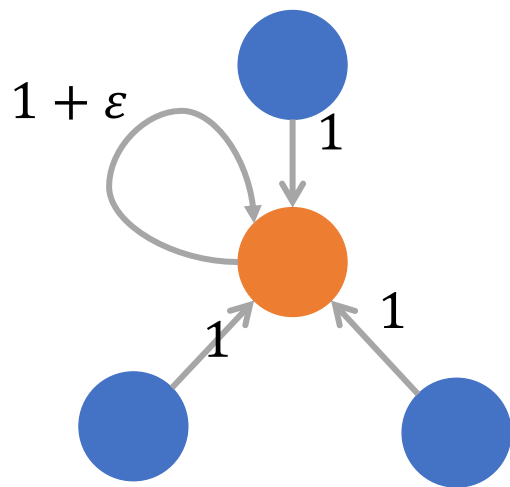


如果将中心节点与邻居节点互换



ϵ 保证了中心与邻居节点可区分

GIN代码解析



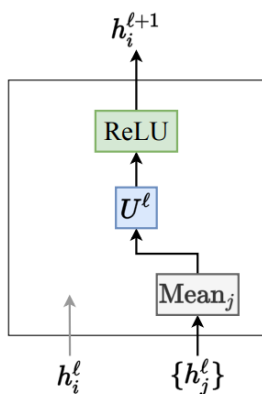
```
def send_src_copy(src_feat, dst_feat, edge_feat):  
    return src_feat["h"]
```

```
msg = gw.send(send_src_copy, nfeat_list=[("h", feature)])  
output = gw.recv(msg, "sum") + feature * (epsilon + 1.0)
```

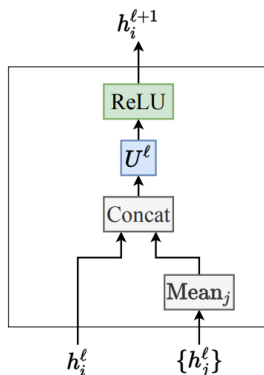
```
output = L.fc(output, size=hidden_size)
```


邻居聚合

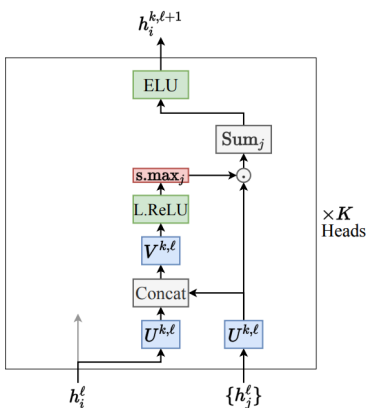
还有更复杂的聚合函数...



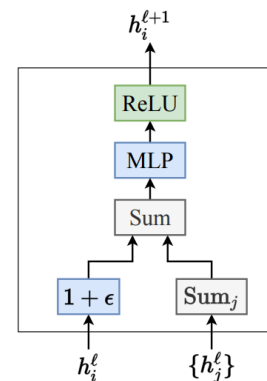
GCN



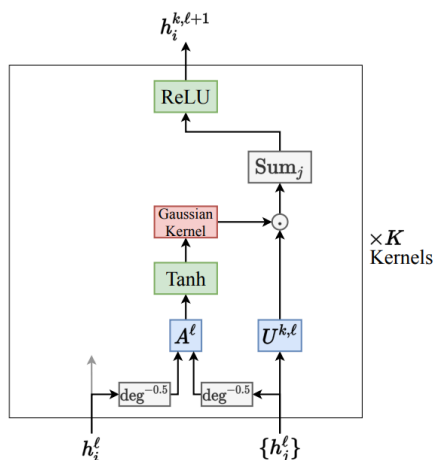
GraphSage



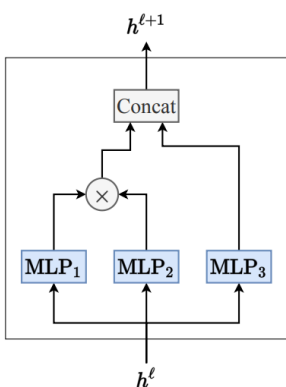
GAT



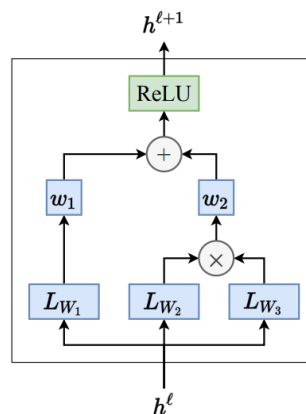
GIN



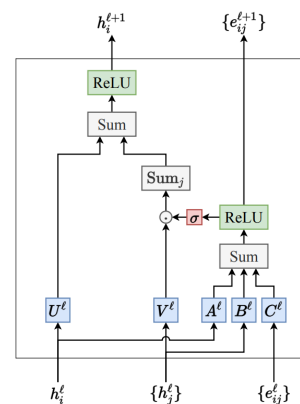
MoNet



3WL-GNN

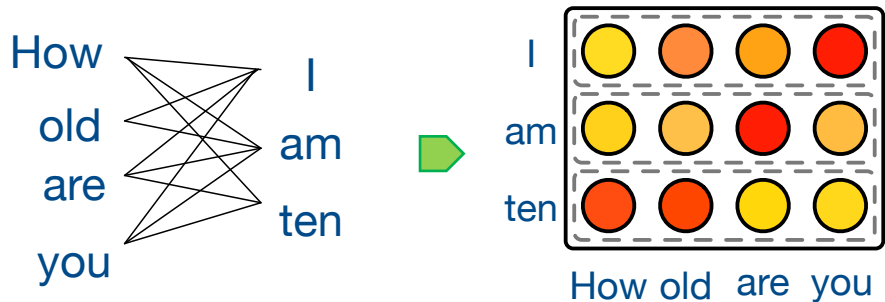


RingGNN

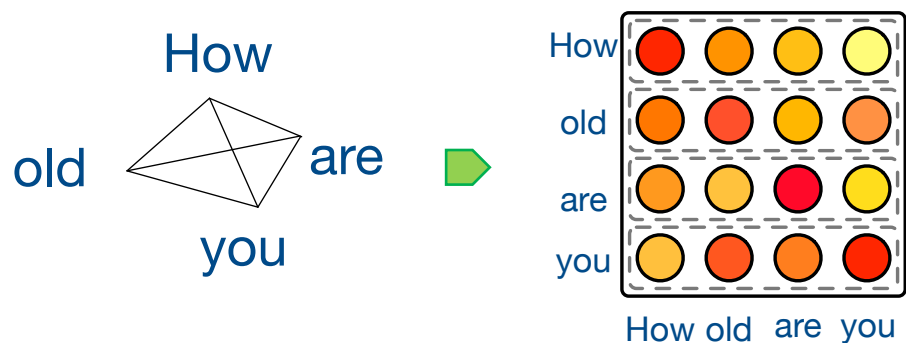


GatedGCN

邻居聚合-语义场景

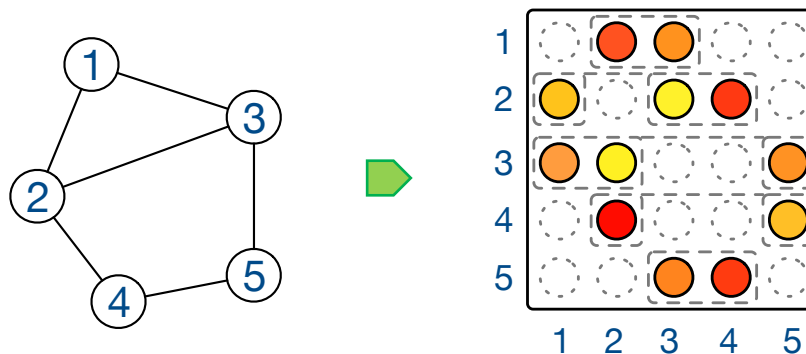


Vanilla-Attention (二分图)



Self-Attention (全连通图)

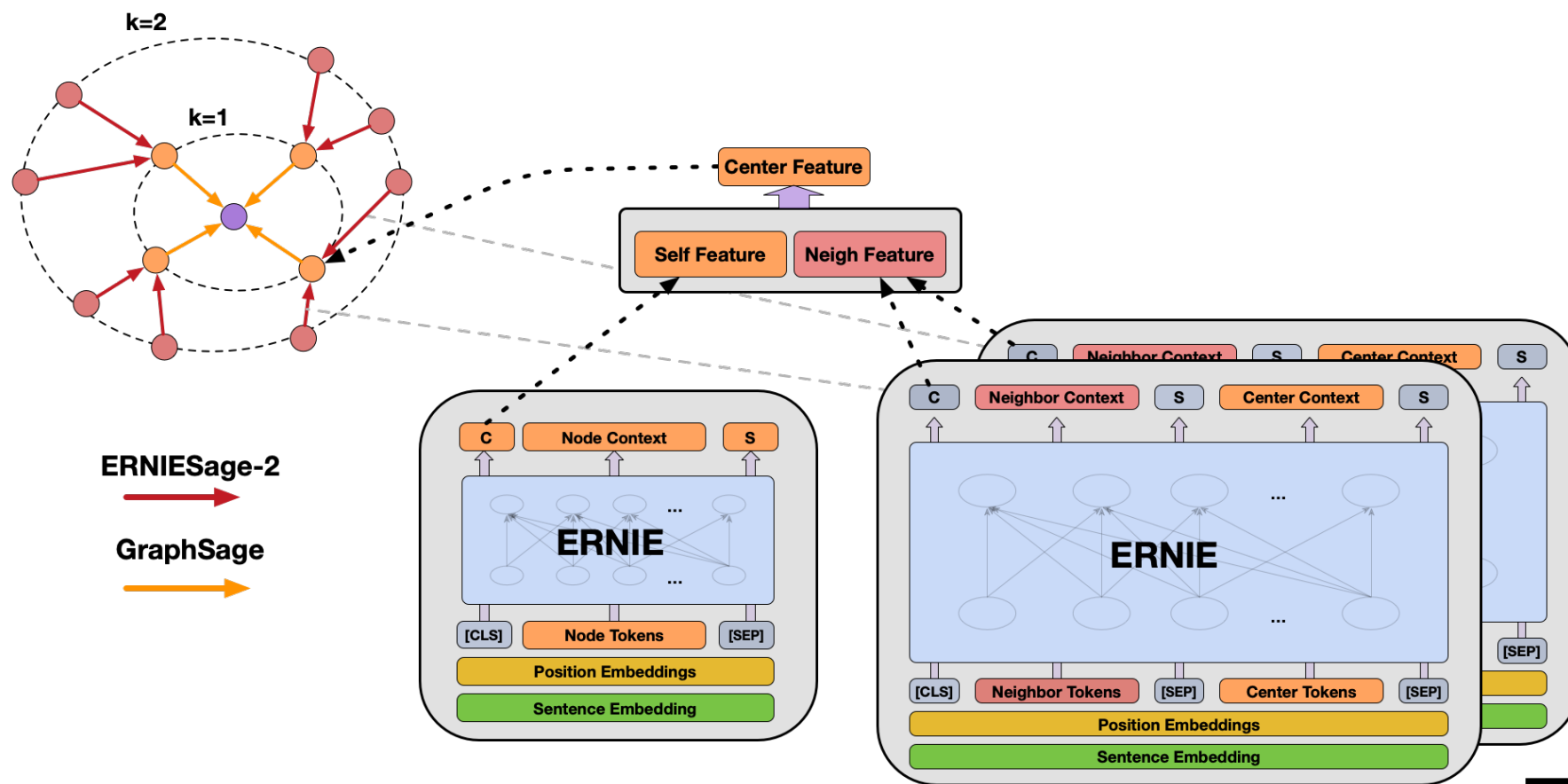
传统NLP领域的Transformer就是全连通图的图模型



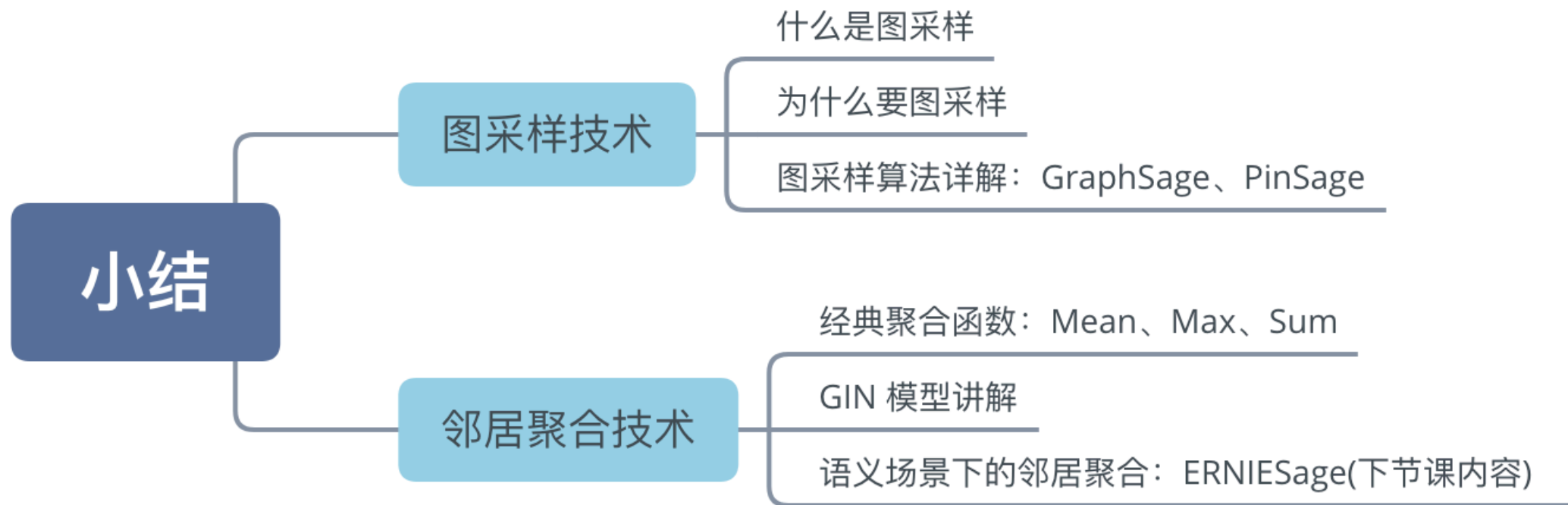
Graph-Attention (任意图)

邻居聚合-语义场景

ERNIESage：在文本图（TextGraph）场景下，使用**ERNIE**做聚合函数

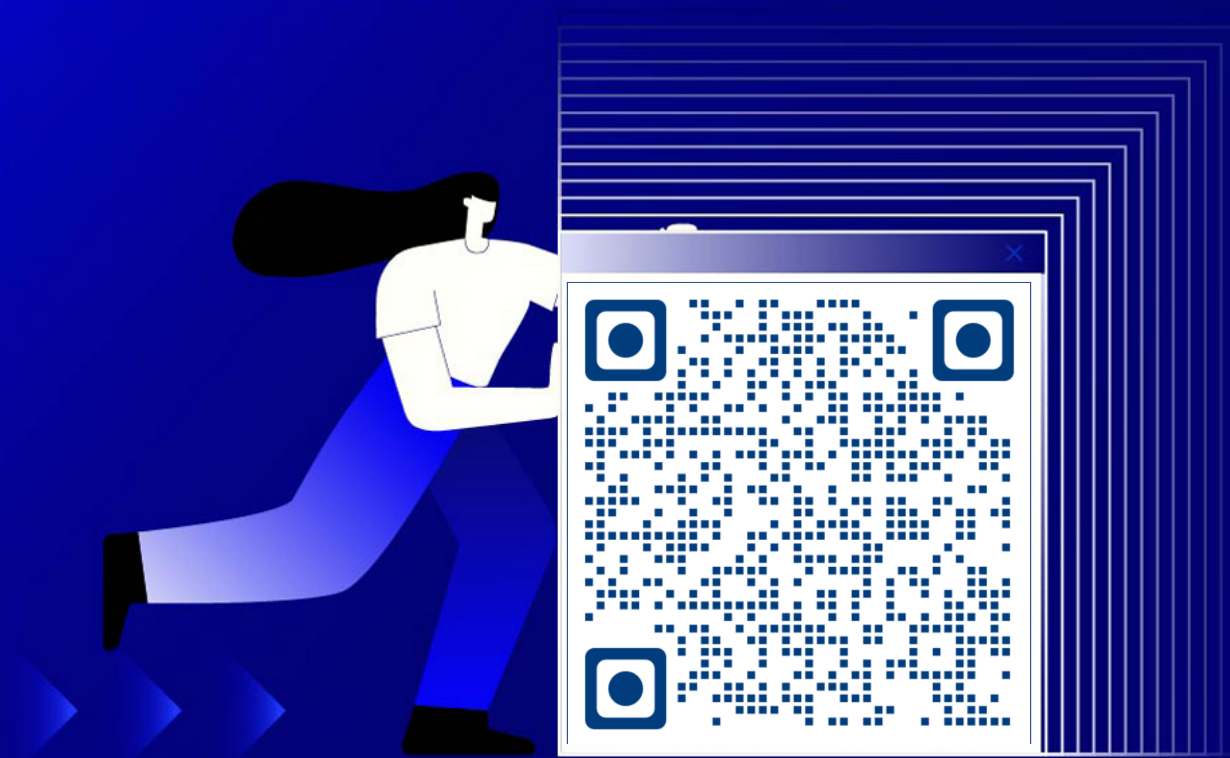


下节课独家解密



有请帅哥老师讲解 GraphSage 采样代码

完成 GraphSage 模型的采样与聚合代码



PGL github

谢谢观看